

**Appendix 1.1. Statement of Supplier**

Supplier name	KEBA AG
Supplier address	Gewerbepark Urfahr
City	4041 Linz
Country	Austria
Telephone	+43 732 7090-0
Fax	+43 732 7090-66630
Email address	<a href="mailto:kamp@keba.com">kamp@keba.com</a>
Product Name	KeMotion
Product version	02.40
Release date	05.10.2011

I hereby state that the following tables as filled out and submitted do match our product as well as the accompanying user manual, as stated above.

Name of representation (person): Harald Kampenhuber

Date of signature (dd/mm/yyyy): 10.10.2011

Signature:



## Appendix 1.5. Short overview of the Function Blocks

Coordinated Function Blocks	Supported Yes / No	Comments (<= 48 char.)
MC_AddAxisToGroup	N	
MC_RemoveAxisFromGroup	N	
MC_UngroupAllAxes	N	
MC_GroupReadConfiguration	N	
MC_GroupEnable	N	RCE_GroupPower is used instead
MC_GroupDisable	N	RCE_GroupPower is used instead
MC_GroupHome	N	
MC_SetKinTransform	N	
MC_SetCartesianTransform	N	
MC_SetCoordinateTransform	N	
MC_ReadKinTransform	N	
MC_ReadCartesianTransform	N	
MC_ReadCoordinateTransform	N	
MC_GroupSetPosition	N	
MC_GroupReadActualPosition	N	RCE_GroupReadTCPData is used instead
MC_GroupReadActualVelocity	N	RCE_GroupReadTCPData is used instead
MC_GroupReadActualAcceleration	N	RCE_GroupReadTCPData is used instead
MC_GroupStop	N	
MC_GroupHalt	N	
MC_GroupInterrupt	Y	
MC_GroupContinue	Y	
MC_GroupReadStatus	N	Not compliant, GroupHoming, GroupStopping not supported
MC_GroupReadError	N	
MC_GroupReset	Y	
MC_MoveLinearAbsolute	N	
MC_MoveLinearRelative	N	
MC_MoveCircularAbsolute	N	
MC_MoveCircularRelative	N	
MC_MoveDirectAbsolute	N	
MC_MoveDirectRelative	N	
MC_PathSelect	Y	
MC_MovePath	Y	
MC_GroupSetOverride	Y	
Coordinated	Supported Yes / No	Comments (<= 48 char.)
MC_SyncAxisToGroup	N	
MC_SyncGroupToAxis	N	
MC_SetDynCoordTransform	N	
MC_TrackConveyorbelt		Is done by robot control. Use RCTracking.lib to do conveyorbelt operations.
MC_TrackRotaryTable		Is done by robot control.

**Table 5: Short overview of the Function Blocks**